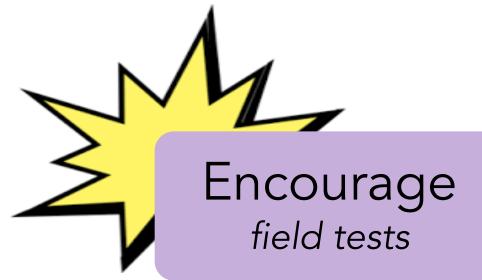
Patrols Deter Poachers: Causal Inference with Bayesian Modeling and Field Tests as a Shock

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A Causal Study of Deterrence Answering a long-standing question in conservation: Are poachers deterred by ranger patrols?

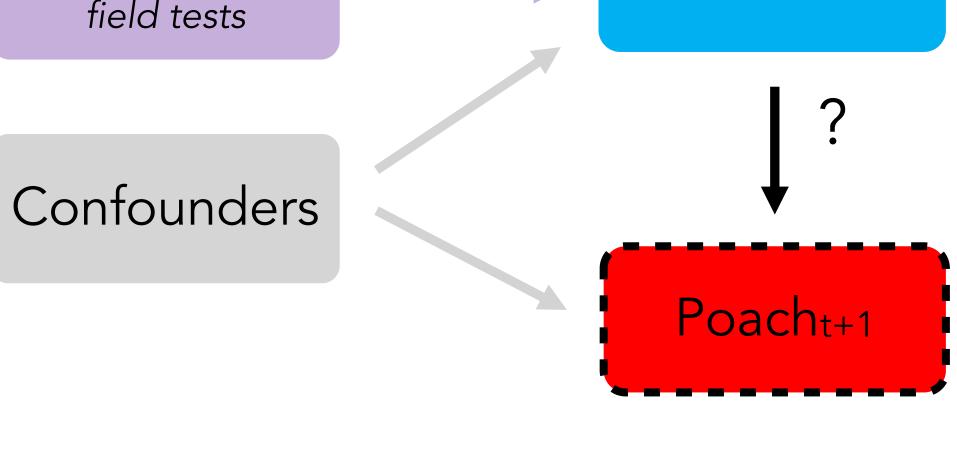


Ranger removing a snare. Photo: Wildlife Conservation Network.

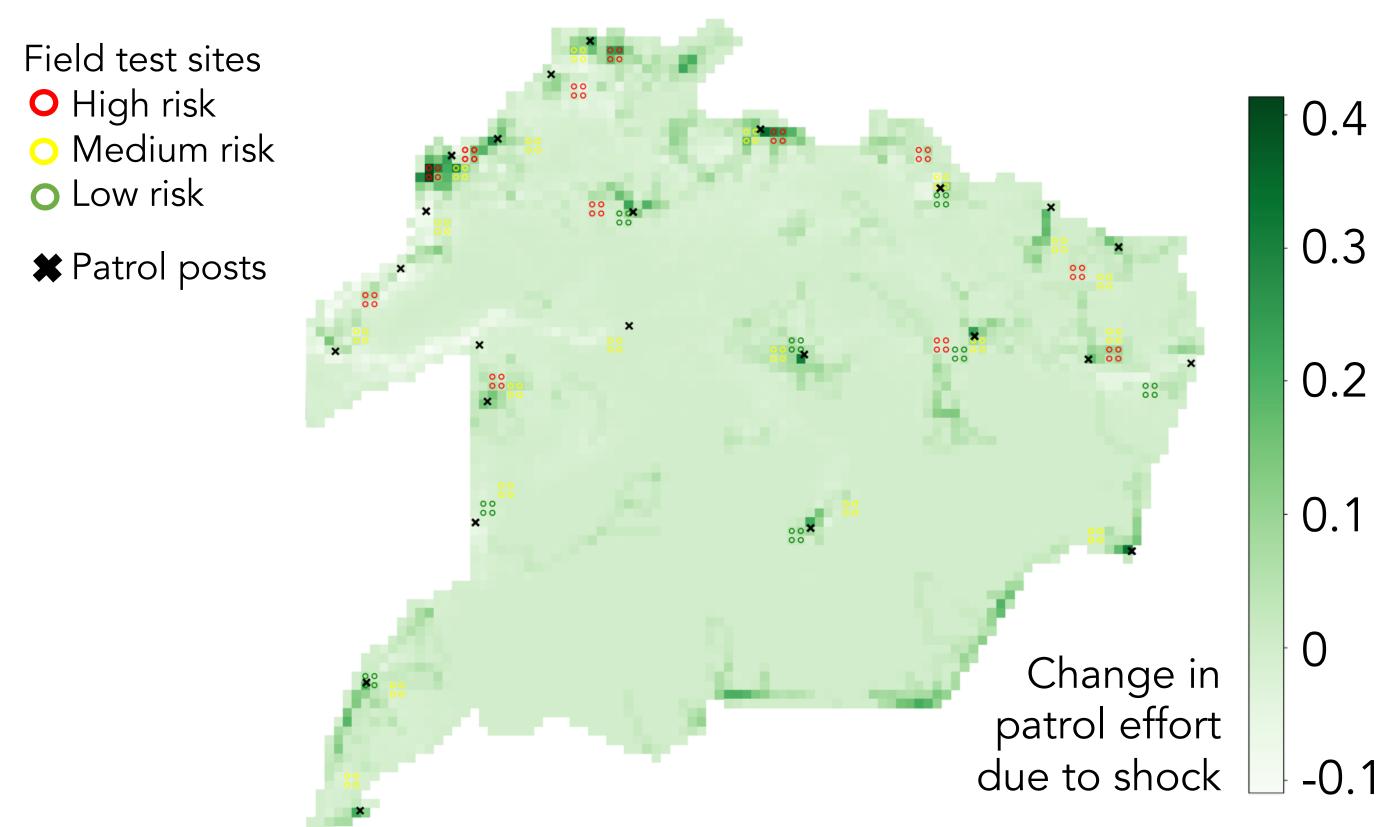




Murchison Falls National Park in Uganda. Photo: Plumptre et al. 2015.



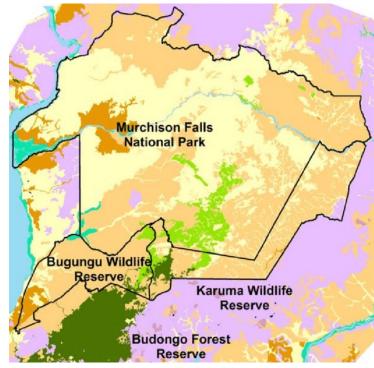
Key Challenge 1 RCTs not feasible \rightarrow Historical field tests as shock to system affecting patrols







Hippos in Murchison Falls National Park. Photo: Wikimedia Commons.



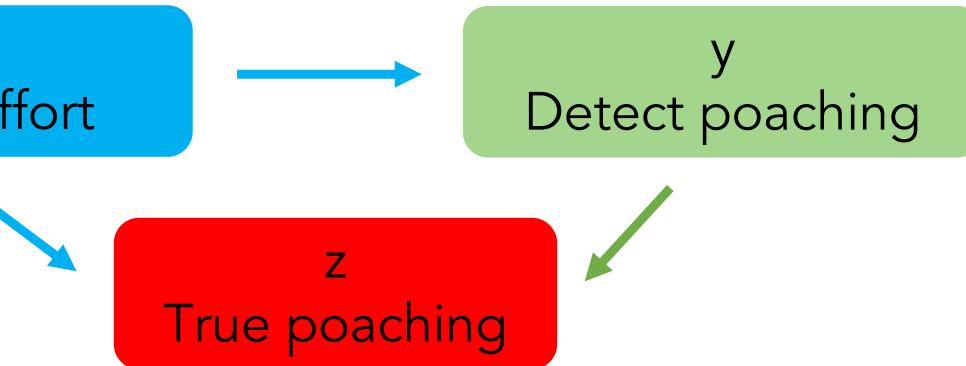


0.4 0.3 0.2 0.1

Imperfect detection of snares \rightarrow Impute

Bayesian model for imperfect detection: Modeling true presence of illegal activity

Patrol effort



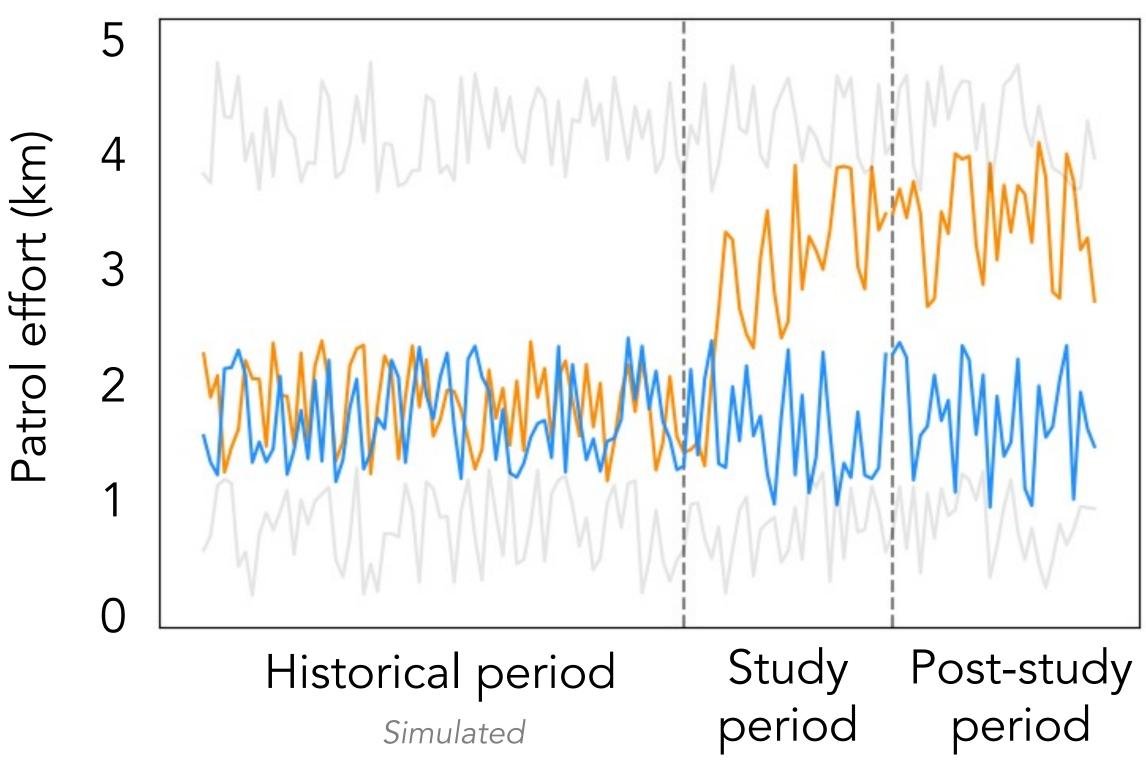
Goal: learn z, which is not observed, using y and x using neural network predictions and domain insight

 $p(z \mid y, x, f) = \begin{cases} p(z \mid f)p(\neg y \mid x, z, f) \\ \overline{p(\neg z \mid f) + p(z \mid f)p(\neg y \mid x, z, f)} \end{cases}$

domain insight $\longrightarrow p(z \mid f) = \lim_{x \to \infty} p(y \mid x, f)$ geospatial features (static and dynamic) $= 1 - p(y \mid x, z, f)$ $= 1 - \frac{p(y \mid x, f)}{p(y \mid x, f)}$ NN model output $p(z \mid f)$

$$p(\neg y \mid x, z, f) =$$

Key Challenge 3 Confounding in observational data \rightarrow Match sites with similar historical patrolling and different study-period patrolling



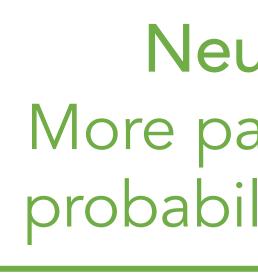


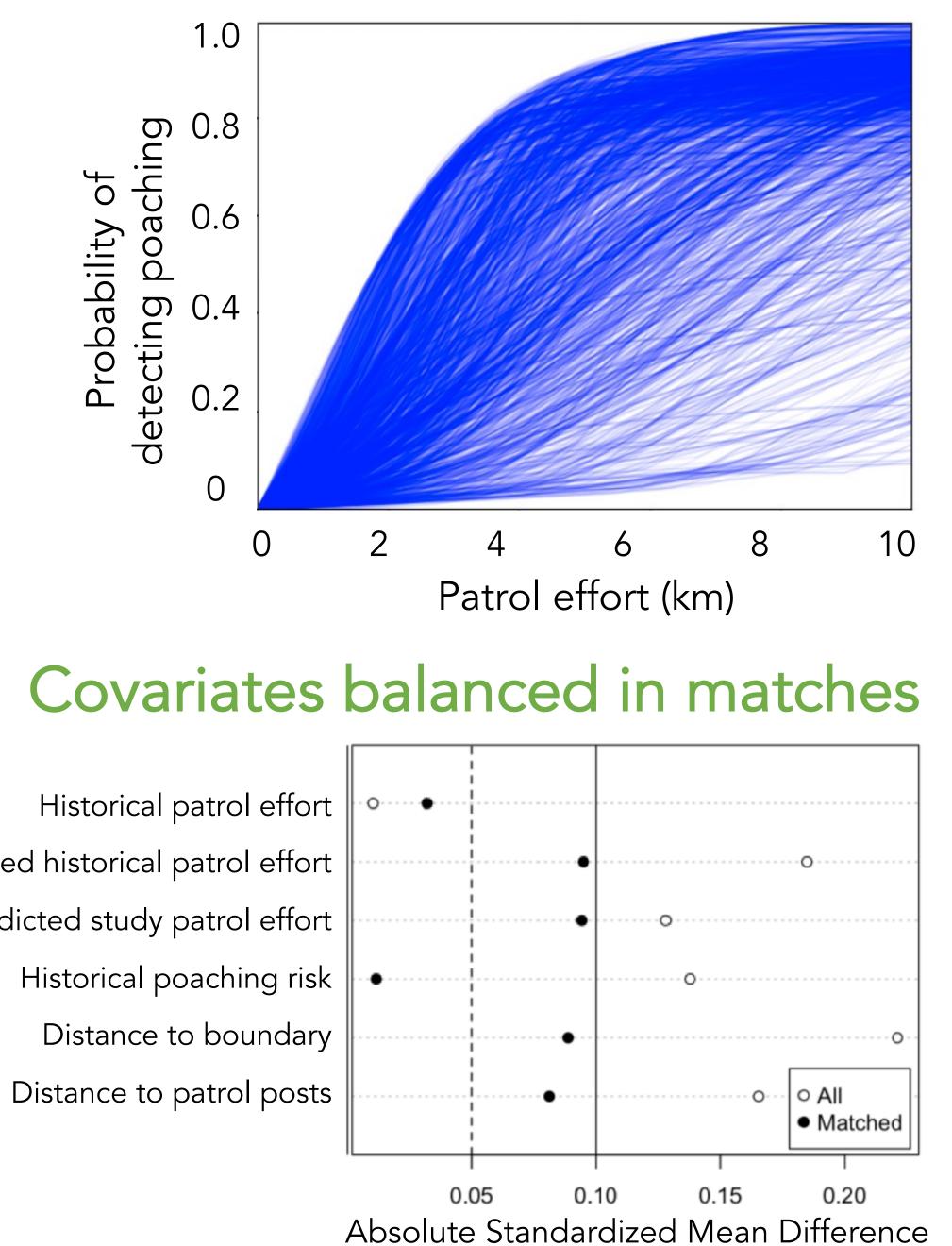
Acknowledgments: Thank you to Uganda Wildlife Authority for the collaboration and data from Murchison Falls National Park.



if y = 0

if y = 1





Predicted historical patrol effort Predicted study patrol effort

Weighted logistic regression Regress imputed post-study poaching outcomes on change in patrol induced by shock using weights from matching

Causal Effect

-0.313

An additional unit of patrolling from expectation causes an average reduction in the log odds of poaching probability by 0.313. First causal result.











Perrault

Neural network learning More patrol effort leads to higher probability of detecting poaching

t	Robust Std. Err.	95% conf. interval
	0.135	[-0.578, -0.047]

Deterrence!